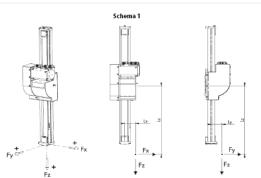


## Vertical rodless electric actuators

Company	
Compiled by	
Date	





			Duty Cycle								
Phase No.	1	2	3	4	5	6	7	8	9	10	
Stroke mm +/-: according directions convention, see scheme 1											
Time (s)											
Mass to displace (kg) (i.e. gripper + part masses to move)											
EXTERNAL FORCE APPLICATION POSITION (MM) + or -: according	directions co	nvention, see	scheme 2								
Xg											
Yg											
Zg											
EXTERNAL FORCE (N) (I.E. CYLINDER/SPRING FORCE TO CON	ITRAST) +	/ - : according	directions co	nvention, see	scheme 1						
Fx											
Fy											
Fz											
CENTER OF GRAVITY MASS TO DISPLACE POSITION (MM) + or	-: according	directions co	nvention, see s	scheme 2							
Lx											
Ly											
Lz											
Usefull stroke requested (mm)											
Any space limitations											
Axis must work "in position" mode (i.e. reaching a defined position, reacting against external forces), or "in torque" mode (i.e. pushing with controlled force against external obstacles in position not defined)?											
No. of hours/day worked (h/d)											
ENVIRONMENTAL CONDITIONS											
Temperature °C / Humidity											
Severity of environment use presence of dust, processing chips, etc.											
Any motor and driver other than Metal Work standard											
ACCESSORIES											
cables tray chain											
Motor cable length											
Available supply voltage											
The check will be done with:	□ PLC v	vith step-di	r board and r board and ess axis boa	"Open Col	er" signals lector" sign	nals					
Short description, notes and draw of the possible application:											